

RESEARCH ARTICLE



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'SOLS' ARCHITECTURE BASED DESIGN OF FM0/MANCHESTER ENCODER AND IMPLEMENTATION ON 'FPGA'

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ABSTRACT

(DSRC) abbreviated as dedicated short-range communication is associated as the rising technique to push the intellectual installation into existing ones. Some of the problem such as DC-balance, enhancement of signal irresponsibility is successfully handled by FM0 and Manchester codes that are the standard for DSRC. The coding-diversity between the FM0 and Manchester codes becomes the serious area to work which seriously limits the potential to reused VLSI design. In this paper, the similarity-oriented logic simplification (SOLS) technique is projected to strike this limitation. SOLS is a technique that improves the hardware utilization rate at some present for each FM0 and Manchester encodings. The coding capability of this paper will totally support the DSRC standards of America, Europe, and Japan. This paper not solely develops a completely reused VLSI design, however additionally exhibits Associate in tending economical performance compared with the established works and also implement the outcome of the technology with the help of FPGA.

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INTRODUCTION

The dedicated short range communication is a protocol for one or two way medium range communication. The DSRC can be briefly classified into two categories: automobile-to-automobile and automobile-to roadside. In automobile-to-automobile, the DSRC enables the message sending and broadcasting among automobile. The automobile-to roadside focuses on the intelligent transportation service, such as electronic toll collection (ETC). The DSRC architecture having the transceiver. The microprocessor is used to transfer the instruction to the baseband processing and RF front end. The RF front end is used to transmit and

receive the wireless signals using the antenna. The baseband processing is responsible for modulation, error correction, encoding and synchronization. The transmitted signal consists of the arbitrary binary sequence; it is very difficult to obtain the dc-balance. The fm0 and Manchester is providing the transmitted signal and then the dc-balance. The (SOLS) similarity oriented logic simplification having the two methods: area compact retiming and balance logic operation sharing. The area compact retiming used to reduce the transistor counts. The balance logic operation sharing is used to combine the fm0 and Manchester encoding. All the bits of the binary data in Manchester coding technique are

arranged in a particular sequence. In this code bit '1' represents by high voltage which represents the half duration of a cycle and for the next half cycle an inverted signal will be send. In this format low voltage will send for the first half cycle when transmitting '0' and for the next half cycle a high voltage is send. There is a condition occur when it is difficult to define how many number of 1s and 0s in the data when sending a data having continuous high signals or continuous low signal (e.g.:11111110000000), Because there is no alteration from low to high or high to low for a particular time period. The only way to find it is to calculate the time duration of a signal but it is not reliable. So this condition can be avoided by using the coding technique in this paper Manchester and fm0 format are use. In Manchester format there will always be a transition from low to high or high to low for each bit. As a result by using Manchester coding the error probability becomes low and data received by the receiver is same as the code word and it becomes easier to detect data from channel for receiver.

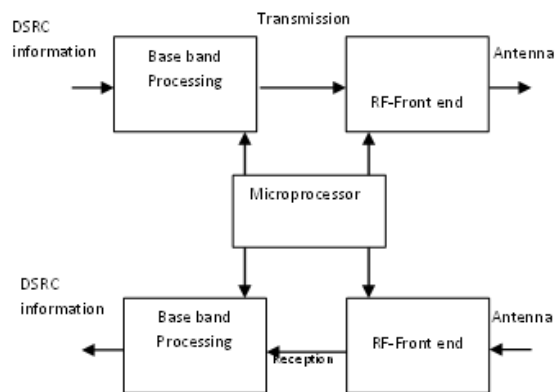


Fig 1: DSRC Transceiver

The system architecture of DSRC transceiver is shown in Fig. 1. The upper and bottom parts are dedicated for transmission and receiving, respectively. This transceiver is classified into three basic modules: microprocessor, baseband processing, and RF front-end. The baseband processing is responsible for modulation, error correction, clock synchronization, and encoding. The RF frontend transmits and receives the wireless signal through the antenna. The microprocessor interprets instructions from media access control to

schedule the tasks of baseband processing and RF front-end.

Literature Review

The VLSI architectures of FMO and Manchester encoders are reviewed as follows Reference [1] proposed a fully reused VLSI architecture using SOLS technique for both FMO and Manchester encoding. The proposed method works on some parameters like TSMC, maximum operating frequency, Power consumption etc. Reference [2] glitch is introduced at the input of MUX-1 that causes logic-fault on coding. This problem is solved by using XNOR with the inverter. Reference [3, 4, 5, and 6] presents review on a review on Evaluation of various forms of DSRC system based on FMO/ Manchester encoding using SOLS technique and also compare this technique with other techniques. Reference [7, 8] proposed a fully reused VLSI architecture using SOL's technique for both FMO and Manchester encodings. The SOLS technique improves the hardware utilization rate from 57.14% to 100% for both FMO and Manchester encodings. Reference [9] proposed a system to minimizing the problem of coding-diversity between FMO and Manchester encodings that causes the limitation on hardware utilization of VLSI architecture design. This paper is realized in180nm technology with outstanding device efficiency. The power Consumption is 29392.843nW for Manchester encoding and FMO encoding. Reference [10] proposed SOLS technique to overcome the problem of hardware utilization of VLSI design used for the DSRC dedicated short-range communication. The SOLS technique improves the hardware utilization rate from fifty seven.14% to 100% for each FMO and Manchester encodings. Reference [11] proposed a method for power reduction in VLSI architecture using FMO and Manchester encoding. The power consumed is 0.72 mw for Manchester encoding. The power consumption is 0.14 mw for FMO encoding. Reference [12, 13, 14, 15] the paper presents coding diversity between FMO and Manchester encodings that causes the limitation on hardware utilization of VLSI architecture design. The SOLS technique improves the Hardware Utilization Rate (HUR) from 57.14% to 100% for both FMO and

Manchester encodings. Reference [16] presents Miller encoding which is integrated with FMO and Manchester encoding architecture for the application of Dedicated Short Range Communication (DSRC). This paper not only develops a fully reused VLSI architecture, but also exhibits a competitive performance compared with the existing works. In reference [17, 18] SOLS technique eliminates the limitation on hardware utilization by two core techniques: area compact retiming and balance logic-operation sharing. The area-compact retiming relocates the hardware resource to reduce the transistors. The balance logic-operation sharing efficiently combines FMO and Manchester encodings with the identical logic components.

Coding Principle of FMO And Manchester Code

Coding principles of FMO code and Manchester code is describe as follows.

For any coding scheme there is a need of Input data represented by X and a clock signal represented by C respectively. And with the help of some basic principle of such coding scheme the data be encoded decoded. Such that the principle of Manchester and FMO coding scheme and such conditions are discussed below.. A. FMO Encoding is shown in Fig. 2, for each X, the FMO code consists of two parts: one for former-half cycle of CLK A and the other one for later-half cycle of CLK B. The coding principle of FMO is listed as the following three rules.

- 1) If X is the logic-0, then there is a transition between A and B.
- 2) If X is the logic-1, no transition is acceptable between A and B.
- 3) The transition is achieved among each FMO code no matter what the X is.

Example of FMO coding is shown by Fig.2. Here the wave form is represented for the first cycle is such that X is logic-0; therefore, a transition occurs at the middle of the bit duration, according to rule 1. For simplicity, this transition is initially set from logic-0to1. According to rule 3, a transition is takes place at each end of the bit, and thereby the logic-1 is changed to logic-0 in the establishment of cycle 2. Then, according to rule 2, this logic-level is hold without any transition in entire cycle 2 for the X of

logic-1. Thus, the FMO code of each cycle can be derived with these three rules mentioned earlier.

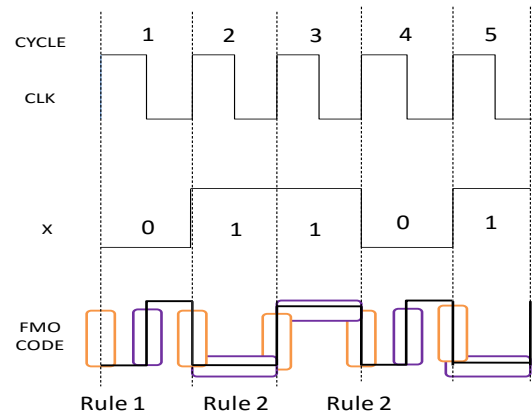


Fig 2: Example of FMO Encoding

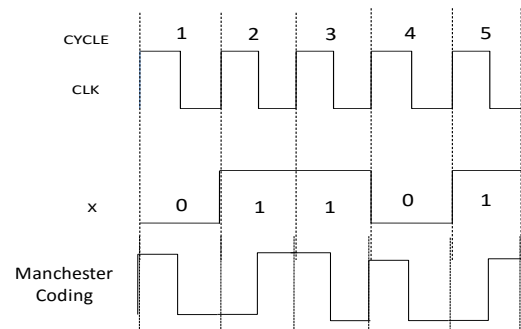


Fig 3: Example of Manchester Coding

XOR operation is used to perform the basic principle of Manchester encoding between clock and input signal. Manchester encoder always changes its state between the centres of each cycle. The Manchester coding example is shown in Figure. 3.

Hardware Architecture of FMO And Manchester Code

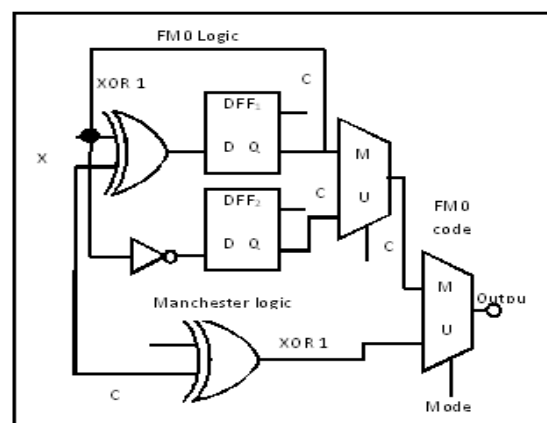


Fig 4: Hardware architecture of the fm0/Manchester code

Figure 4 represents the hardware architecture of proposed model. The upper part is denoted the fm0 code and then the bottom part are denoted as the Manchester code. In fm0 code the DFF1 and DFF2 are used to store the state code of the fm0 code and also mux_1 and not gate is used in the fm0 code. When Mode value is '0' fm0 code is work. When Mode value '1' is selected then it gives output as Manchester code and this code is develop only by XOR the data with the clock. The hardware utilization rate is defined as the following. The HUR rate is given below the following section

$$HUR = AC/TC * 100 \%$$

AC- Active Components

TC- Total components

- Active components means the components are work in the both fm0 and Manchester code.
- The total components means the number of the components are present in the whole circuit.

Proposed SOLS Technique for FM0 and Manchester Design

(SOLS) similarity-oriented logic simplification technique improves the hardware utilization rate at some present for each FM0 and Manchester encodings. The SOLS technique is classified into two parts area compact retiming and balance logic operation sharing.1) in area compact retiming is shown by figure 5. Fm0 the state code of the each state is stored into two D flip flop DFF1 and DFF2. The Change in the state depends on state code that depends on the previous state of D flip-flop 1 i.e., 1(t-1) instead of the both the flip-flop. The previous state of both the flip-flop is denoted by 2(t-1) and 1(t-1) and 2(t), 1(t) represents the current state.

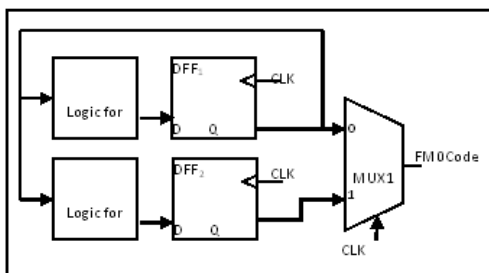


Fig 5: Area Compact Retiming

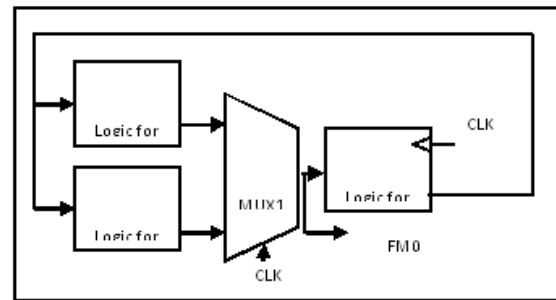


Fig 6: FM0 encoding without area compact retiming To store the single bit output of the FM0 D-flip-flop is used that stores the previous state of the coding to generate the next one. As shown in figure 6 d flip-flop is used and the output of the fm0 depends on both the flip-flop it generates the output by comparing present data of both flip-flop 2(t) and 1(t). This is done to avoid the asynchronous faults. DFF1 is assumed to be positive-edge triggered flip flop shown in figure 6. At each cycle, the FM0 code, comprising 2 and 1, is derived from the logic of 2(t) and the logic of 1(t), respectively.

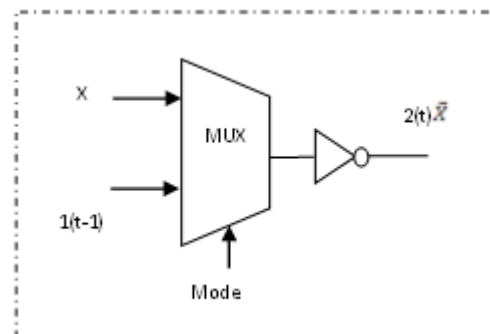


Fig 7: FM0 encoding with area compact retiming

By using the CLK signal in the MUX_1 the output of the flip-flop is switch between D flip-flop 1(t) and 2(t). The output of the DFF1 is directly updated from the logic of 1(t) with 1- cycle. When the CLK is logic-0, the output of DFF1 1(t) is given to the MUX-1. Then the upcoming positive-edge of CLK updates it to the Q of DFF

1. The timing diagram for the Q of DFF1 is consistent whether the DFF1 is relocated or not.
2. Balance logic operation shearing: XOR operation is used to generate the logic of Manchester encoding. The equation of the XOR gate is given below.

$$X \text{ XOR CLK} = X \overline{\text{CLK}} + \overline{X} \text{ CLK}$$

The concept of balance logic-operation sharing is to incorporate the X into both flip-flop output 2(t) and

1(t). MUX_2 decides the mode whether the output is taken from the fm0 or Manchester. Figure 8 represents the logic for balance logic sharing given the following.

Here, MUX Mode defines the Output is FM0/Manchester. If Mode is '0' that means the output is FM0 and if Mode is '1' then output is Manchester. The $2(t)/\bar{X}$ can be derived from an inverter of $1(t-1)$, and X. The logic for $2(t)/\bar{X}$ can share the same inverter, and then a multiplexer is placed before the inverter to switch the operands of $1(t-1)$ and X. The Mode of the MUX indicates either FM0 or Manchester encoding. The similar concept can be also applied to the logic for $1(t)/X$. Nevertheless, this architecture exhibits a drawback that the HUR of this architecture is limited because XOR is only dedicated to FM0 encoding, and is not shared with Manchester encoding. The X can be also interpreted as the X 0, and thereby the XOR operation can be shared with Manchester and FM0 encodings, where the multiplexer is not responsible to switch the operands of $1(t-1)$ and logic-0. This architecture shares the XOR for both $1(t)$ and X, and thereby increases the HUR.

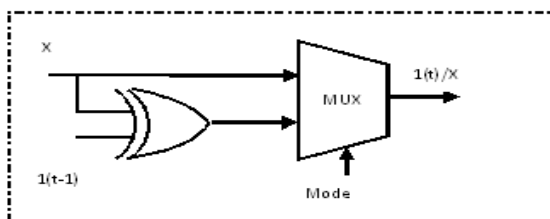


Fig 8: Balance logic operation sharing

Discussion of Results

The present design is simulated and synthesized using Xilinx ISE Tool. Fig-9 and Fig.10 show the Block Diagram and the RTL Schematic diagrams of FM0-Manchester Encoder design based on simulation. Fig.11 Represent the waveform simulation diagram of the encoder design.



Fig 9: Block diagram of FM0/Manchester Encoder

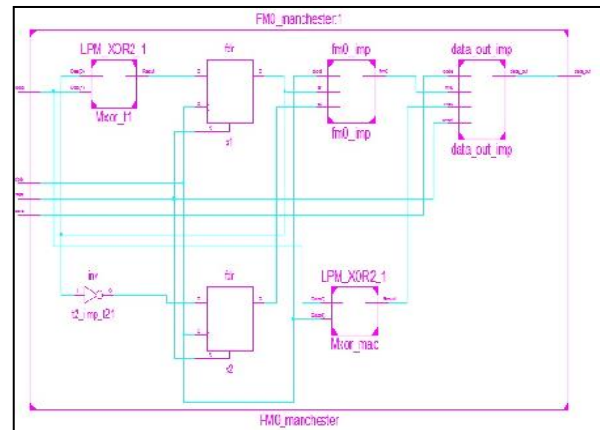


Fig10: RTL diagram of FM0/Manchester encoder

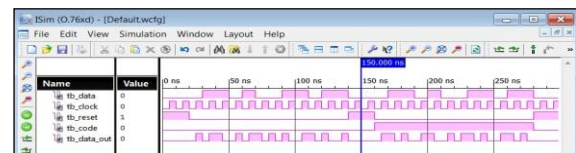


Fig 11: Represent the waveform simulation diagram of the encoder design

Xilinx Spartan3 FPGA is use to implement the encoder design. The hardware includes FPGA Kit, LCD 16x2 Display and Push-button board. Fig-12 shows the arrangement of the implementation kit setup and Fig-13 shows reset mode operation display on LCD.

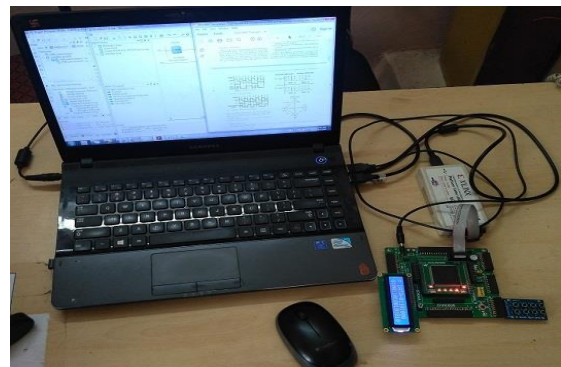


Fig.12: Hardware architecture of FM0/Manchester Encoder



Fig.13: FM0-Manchester - Reset Mode Display The hardware based design simulation is performed

on various input values. An example with input value "01101000" is shown for both FM0 and Manchester operational modes in Fig-14 and Fig-15 respectively.

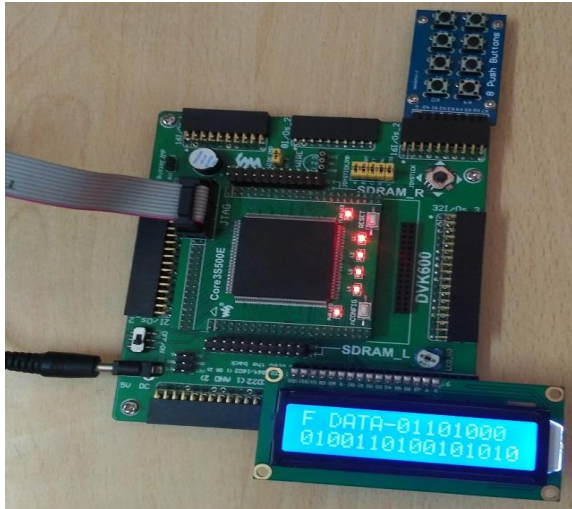


Fig 14: FM0 Input Example Display

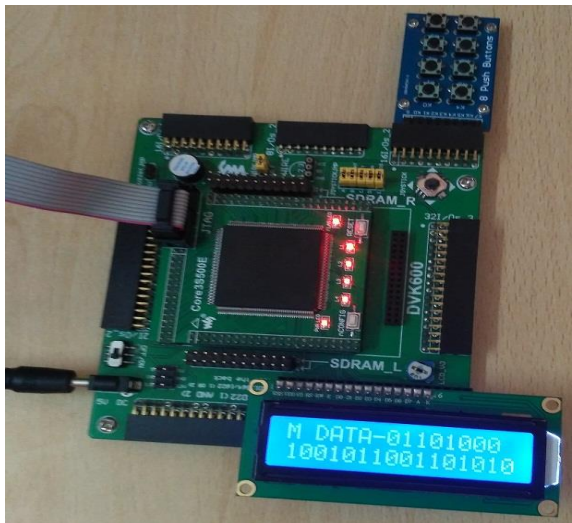


Fig 15: Manchester Input Example Display

The FPGA based hardware utilization summary of the implemented Encoder design is presented in Table-I and Table-II respectively. The hardware utilization is presented for software simulation based design and hardware implementation design.

TABLE I: Hardware Utilization of FM0/Manchester Encoder (Software Design Simulation Encoder)

Spartan-3E XC3S500E-4PQ208	Total	FM0-Manchester Encoder	
		Used	%
Slices	4656	2	0
Flipflops	9312	2	0

Spartan-3E XC3S500E-	Total	FM0-Manchester Encoder	
LUTs 4-Inputs	9312	4	0
Bonded IOBs	158	5	3

TABLE II: Hardware Utilization of FM0/Manchester Encoder (Software Design Simulation Encoder)

Spartan-3E XC3S500E-4PQ208	Total	FM0-Manchester Decoder	
		Used	%
Slices	4656	299	6
Flipflops	9312	244	2
LUTs 4-Inputs	9312	441	4
Bonded IOBs	158	23	14

These tables give the utilization of the hardware resources of the design in terms of flip-flops and slices. The flip-flops represent the sequential logic components required by the design for logic representation. The slice is a combination of Look-Up-Tables (LUT) and Flip-flops. Different LUTs are present in a FPGA. A LUT is a combination of combinational and/or sequential logic hardware that can be programmed to generate a specific output as per the requirement of design. A comparative analysis of the hardware utilization of the design in the present work with some of the existing works is presented in Table-III.

TABLE III: Comparative analysis of design based on hardware utilization

Reference	Present Work	[19]	[15]	[19]
Device	Xilinx FPGA Spartan 3	Xilinx FPGA Spartan 2	Xilinx FPGA	Xilinx FPGA Spartan2
Slices	2	5	2	1
Flipflops	1	4	2	2
LUTs 4-Inputs	3	10	3	2
Bonded IOBs	5	4	5	3

Conclusion

The limitation on VLSI architecture designing causes due to the coding-diversity between FM0 and Manchester encodings. The limitation analysis of FM0 and Manchester encodings is discussed in detail. Hence, the fully reused VLSI architecture using SOLS (Similarity

oriented logic simplification) technique for both FM0 and Manchester encodings is modified. The SOLS technique eliminates the limitation by two core techniques: area-compact retiming and balance logic-operation sharing. Area-compact retiming relocates the logic elements effectively. The Balance Logic operation sharing technique combines FM0 and Manchester encodings to produce balanced computation time. Results show the improved hardware utilization rate through which power consumption is reduced. This project not only develops VLSI architecture for FM0 and Manchester Encoding but also improves the performance of both encoding schemes.

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