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RESEARCH ARTICLE



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IRIS RECOGNITION SYSTEM USING 2-D DCT AND HAMMING DISTANCE TECHNIQUES

SAKSHI SHARMA , AMRIT PAL SINGH

¹Asst. Professor (Electronics and Communication) ²M.tech (Electronics and Communication) Chandigarh Engineering College, Landran, India

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ABSTRACT

Biometric is a part of science which helps to provide verification and identification of any individual by using different algorithms. Biometrics is classified in to two parts: physiological and behavioral. Physiological part includes hand, DNA, Iris, fingerprint and face. Behavioral part consists of keystroke, signature and voice. This paper works on implementation and verification processes by using Iris patterns. In this work two processes are performed i.e. Implementation and Verification. Results are evaluated in terms of FAR, FRR and Recognition Rate.

Keywords-Iris recognition, UBIRIS, 2-D DCT, Canny edge detector, Hamming distance.

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I. INTRODUCTION

A biometric system can be utilized in two contexts: verification and implementation.

Verification is a process to match one-to-one person's identity. In this process, system tries to verify identity of a person by providing a new data template to the system as input, the system calculate the distance between the newly taken input data and its corresponding gallery sample (previously stored in the database), then it compares the computed distance with a Hamming distance inner class value. If the measured distance issmall then the new sample is accepted, otherwise it is rejected. If an input data template and the stored template are from the same subject then it is known as genuine person and if the input data and the stored data are not from the same subject then it is known as imposter. A Receiver Operating Characteristic (ROC) curve plots the comparison curve between FAR and FRR. The Equal Error Rate (EER) is obtained by using FAR and FRR values. A smaller EER indicates a better performance of the system in case where FAR became equal to FRR. Implementation process is performed in Iris Recognition System to provide authentication to a new user. In this context, feature extracted data template of the user get saved in database. The percentage of total number of false accepted images is known as False Acceptance Rate. The percentage of false rejected images is known as False Rejection Rate. The percentage of true accepted images is known as Recognition Rate.

II. ADVANTAGES OF IRIS RECOGNITION TECHNOLOGY

1) Iris patterns remain unique throughout person's life.

2) No physical contact of any hardware device with eye is required, while capturing eye image of any person.

3) Verification process time of Iris

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Recognition System is less (in seconds).

III. LITERATURE REVIEW

Table I: Literature review							
Researchers Name	Journal	Algorithms Used	Results				
Aparna Gale,	International Journal of	Hough transform, Daugman	FAR=5%				
S.S.Salankar [1]	Engineering and Advanced	rubber sheet model, Haar	FRR=4%				
	Technology, ISSN: 2249 –	transform, Block sum algorithm,	RR=95.5%				
	8958, Volume-4 Issue-4,	Hamming distance technique.					
	April 2015	DATABASE: CASIA					
Saloni Chopra [2]	International Journal of	Canny edge detector, Daugman	FAR=0.22%				
	Scientific Research	rubber sheet model, 2-D Reverse	FRR=5.33%				
	Engineering & Technology	biorthogonal wavelet transform,	RR=97.22%				
	(IJSRET), ISSN 2278 – 0882,	Hamming distance.					
	Volume 3, Issue 3, June	DATABASE: UBIRIS					
	2014						
AnapManishaBaban	International Journal of	Hough transform, 2-D log Gabor	FAR=0.07%				
[3]	Application or Innovation	filter, Hamming distance	FRR=0%				
	in Engineering &	technique.	RR=99.96%				
	Management, Volume 3,	DATABSE: CASIA					
	Issue 5, May 2014						
Mohd. T. Khan [4]	Contemporary Computing	Freeman's chain code, 1-D log	FAR=3.87%				
	(IC3), Sixth International	Gabor filter, Hamming distance	FRR= 9.29%				
	Conference, 8-10 Aug.	technique.	RR= 93.42%				
	2013, Publisher: IEEE	DATABASE: UBIRIS					
Shabaan A. Sahmoud	Elsevier Ltd., DOI:	K-means clustering, Circular	FAR=1.5%				
[5]	10.1016/j.patcog.2013.06.	Hough transform, Libor Masek	FRR=5.82%				
	004, 2 June 2013	technique, Hamming distance.	RR=96.34%				
		DATABASE: UBIRIS					

IV.METHODOLOGY

Methodology is divided into two parts: implementation and verification.

A) Implementation process: This process helps to provide authentication to a new person by storing new binary data template in database.

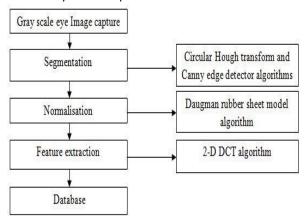


Figure 1:Implementation process

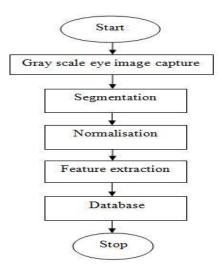


Figure 2: Implementation flow chart

B) Verification process: This process helps to verify the identity of any person by comparing new data template with stored data template. Verification Garyscale eye image capture Segmentation Normalisation Feature extraction Matching Verification Circular Hough transform and Canny edge detector algorithms Daugman rubber sheet model algorithm 2-D Discrete Cosine Transform algorithm

Figure 3: Verification process

V. PROPOSED WORK

A) Implementation:There are three steps involved in implementation process explained below. UBIRIS database grayscale images are captured by using Nikon E5700 camera.

1) Segmentation: In this segmentation grayscale eye images are segmented by using Canny edge detector algorithm.

2) Normalisation: In this step Iris region in radial form is transformed into angular form by using Daugman rubber sheet model.

3) Feature extraction: In this step 2-D DCT algorithm is used which helps to divide image into 16*16 matrix and compress the pixel values. Further compressed image is converted into binary form by usingbinarisation method. These binary data templates are stored in database.

B) Verification: In verification new grayscale image is provided to system as input. Process involves four steps:

1) Segmentation: New input image is segmented as shown in figure (5).



Figure (4): Input Grayscale image

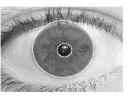


Figure (5): Segmented eye image

2) Normalisation: Segmented image is normalized and features get enhanced by histogram equalization.

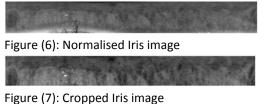




Figure (8): Final features enhanced image

3) Feature extraction: Features are extracted by using 2-D DCT algorithm and converted into binary data template.

4) Matching: In this step, Hamming distance algorithm is used which helps to match new input data template with previously stored data template in database by using following equation.

$$HD = \frac{1}{N} \sum_{j=1}^{N} X_j \oplus Y_j$$

If Hamming distance between new template and stored template is less than threshold, then person is genuine otherwise imposter. In the present case, the person is found genuine.

VI. IMPLEMENTATION RESULTS

System is tested on 200 UBIRIS grayscale images by using MATLAB R2012a. Results are evaluated in terms of FAR, FRR and RR.

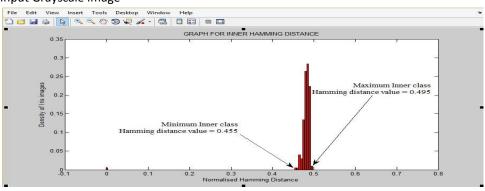
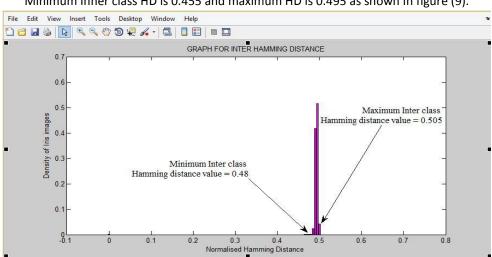


Figure (9): Inner class Hamming distance graph



Minimum Inner class HD is 0.455 and maximum HD is 0.495 as shown in figure (9).

Figure (10): Inter class Hamming distance graph Minimum Inter class HD is 0.48 and maximum HD is 0.505 as shown in figure (10).

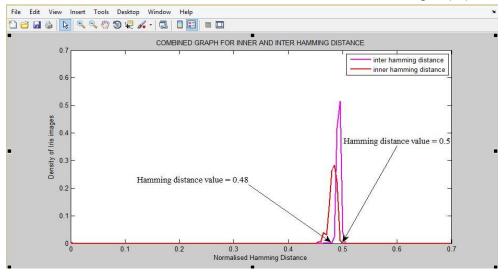


Figure (11): Combined Inner and Inter Hamming distance graph

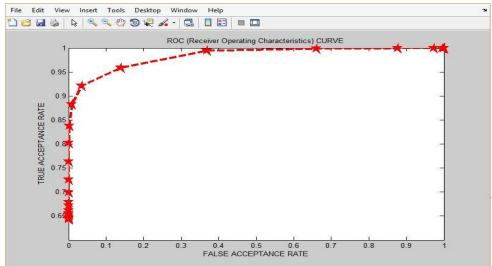


Figure (12): ROC curve(Receiver Operating Characteristics) ROC curve shows high True Acceptance Rate and low False Acceptance Rate.

Table 2: Comparison table					
Researchers	Recognition	FAR	FRR	Database	
name	Rate				
Saloni	97.22%	0.22%	5.33%	UBIRIS	-
Chopra					
Proposed	99.99%	0.0087%	0%	UBIRIS	[8]
work					

VII. CONCLUSION

This paper presents an Iris Recognition System with high Recognition Rate and low FAR, FRR values. In this work Canny edge detector, Daugman rubber sheet, 2-D DCT and Hamming distance algorithms are used. Comparison table is mentioned which shows better results of proposed work than previous work on UBIRIS database.

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